MARCH 12, 2025

SPACE CONCEPT OF OPERATIONS



1.0 INTRODUCTION

1.1. Project Description

In response to emerging operational needs, the United States Space Force sponsor has tasked the AstraLux Space Team with conceptualizing a dual-component system. The first component, the *Sidera I* Spacecraft, is envisioned as a platform to provide persistent observational coverage of both the Northern and Southern Hemispheres of Earth, enabling enhanced situational awareness across a range of operational contexts. The second component, referred to as the STRIKE Application System, is anticipated to enable a full spectrum of targeting, reconnaissance, intelligence gathering, knowledge integration, and engagement support. These functions are intended to operate across all phases of both the kill chain and the intelligence analysis cycle. These capabilities are expected to operate in a coordinated framework that emphasizes responsiveness, precision, and strategic integration across multi-domain operations.

1.1.1 Background

1.1.1.1 Objective and Mission Goals

1.1.1.2 Rationale for System

There is a growing demand for a spacecraft capable of capturing Synthetic Aperture Radar (SAR) imagery to address critical gaps across multiple sections. Satellite-based SAR offers all-weather, day-and-night imaging capabilities that can enhance situational awareness and decision-making.

1. Weather Imaging

a. Disaster Monitoring

Timely detection and monitoring natural disasters are essential for enabling rapid response and recovery efforts. Government agencies such as the Federal Emergency Management Agency (FEMA) rely on accurate, up-to-date imagery to support emergency preparedness, hazard mitigation, and recovery operations. Satellite SAR can provide early warning and situational data for a wide range of weather-related disasters, including floods, droughts, hurricanes, tornadoes, wildfires, and severe winter storms.

b. Environmental Monitoring

Monitoring ecosystem changes is critical for advancing environmental research and supporting the preservation of natural resources and wildlife. Organizations such as the Environmental Protection Agency (EPA), National Park Service, and the Natural Resources Conservation Service, along with academic institutions, depend on consistent, high-

resolution imagery to study environmental transformations. SAR satellites can detect subtle changes in land and water systems caused by climate change, including rising global temperature, sea-level rise, shifting precipitation patters, ocean warming and acidification, desertification, insect outbreaks, deforestation, and urbanization (exempli grata, road and building expansion). They also play a vital role in tracking the status of critical water sources such as ice sheets, glaciers, and river systems.

c. Military and Intelligence

The collection of intelligence, surveillance, and reconnaissance data is a cornerstone of national security operations. Agencies such as the Central Intelligence Agency (CIA), Defense Intelligence Agency (DIA), National Geospatial-Intelligence Agency (NGA), National Security Agency (NSA), National Reconnaissance Office (NRO), and the intelligence branches of the United States Armed Forces rely on persistent, reliable imagery to support strategic decision-making. SAR satellites enhance ISR capabilities by enabling covert, weather-independent observation of global areas of interest, tracking activities, and supporting threat assessments— all of which contribute to protecting United Staes interests and informing foreign policy.

- 2. Agriculture
- 3. Maritime Modeling
- 4. Mapping and Geologic Surveys
- 5. Traffic Monitoring
- 6. Urban Planning

1.1.2 Assumptions and Constraints

The development and deployment of the AstraLux Sidera spacecraft are based on the following assumptions and constraints:

Assumptions

Technology Readiness:

It is assumed that all core subsystems— including Synthetic Aperture Radar (SAR) payloads, onboard autonomy software, fault-tolerant avionics, and secure communications— will reach Technology Readiness Level (TRL) 6 or higher prior to system integration and launch.

Orbital Access:

A viable launch solution to the targeted low Earth orbit (LEO) regime will be availability within the projected deployment timeline.

• Regulatory Compliance:

It is assumed that all relevant spectrum licenses, launch approvals, and orbital debris mitigation plans will be secured through the appropriate United Staes and international regulatory bodies prior to deployment.

Design Team Support Continuity:

Sustaining engineering support will be available from the original design team during at least the first 12 months of on-orbit operations.

Constraints

Deployment Timeline:

The spacecraft must be ready for launch and initial operations within a defined mission window to support aligned intelligence and operational objectives. Delays beyond this window could reduce strategic value.

Size, Weight, and Power (SWaP):

The system must adhere to specified SWaP limitations to ensure compatibility with the selected launch vehicle and onboard power generation capabilities.

• Cybersecurity Compliance:

Flight software must meet stringent cybersecurity requirements, including encryption, access control, and secure update mechanisms.

Budgetary Limits:

Development must be executed within fixed programmatic budget allocations, which may constrain the number of flight units, redundancy features, or extended testing activities.

• Communications Availability:

The spacecraft will rely on a defined set of ground station access windows and network infrastructure. Operational plans must conform to available contact schedules.

1.2 Overview of the Envisioned System

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3.0 DESCRIPTION OF ENVISIONED SYSTEM

3.1 Needs, Goals and Objectives of Envisioned System Synthetic Aperture Radar (SAR) Spacecraft Introduction

To maintain strategic dominance contesting and denied environments, the United States Space Force requires a next-generation SAR spacecraft capable of delivering persistent, all-weather, day-night surveillance to support rapid threat detection, global targeting, and time-sensitive operations.

Traditional electro-optical systems are constrained by weather and lighting. In contrast, SAR technology provides radar imaging that can penetrate cloud cover, operate in darkness, and deliver high-resolution intelligence regardless of atmospheric conditions. This operational versatility is essential for tracking mobile and dispersed adversaries who increasingly exploit concealment, unpredictability, and geographic complexity.

The envisioned SAR system must:

1. Enable Persistent Global Surveillance

Provide continuous coverage over high-interest regions, with the capability to revisit targets frequently and detect movement or changes in near real-time.

2. Deliver Resilience and Redundancy in Space-Based ISR

Support layered surveillance architectures that reduce dependence on single-point systems. The SAR spacecraft should function as part of a disaggregate, survivable ISR network.

3. Achieve Higher Resolution and Faster Refresh Rates

Improve image clarity and cadence to enable precise threat identification, change detection, and pre-strike confirmation in rapidly evolving scenarios.

4. Support Strategic Deterrence and Responsive Targeting

Increase the agility of joint targeting cycles by providing verified intelligence that enables decision-makes to act quickly and confidently.

3.2 Overview of System and Key Elements

The AstraLux Sidera spacecraft system is composed of multiple interdependent subsystems, each responsible for a distinct set of mission-critical functions. These subsystems work collectively to achieve the platform's operational goals, enable data collection and transmission, ensure safe orbital operations, and support onboard payloads. The system is designed to interface with human operators and autonomous support tools through ground-based mission control environments and digital engineering platforms.

At a functional level, the AstraLux Sidera system includes the following major elements:

Attitude Determination and Control Subsystem (ADCS)

Maintains the spacecraft's orientation in space to support mission functions such as Earth-pointing, solar alignment, and payload positioning. This subsystem is responsible for determining current attitude and executing orientation adjustments as needed.

Command and Data Handling (C&DH)

Serves as the central node for processing spacecraft commands and managing internal data flow. It interprets operator directives, executes mission plans, and coordinates the activities of other subsystems.

Electrical Power Subsystem (EPS)

Generates, stores, and distributes electrical power to all onboard systems. This includes power budgeting, load prioritization, and support for varying operational conditions throughout the mission lifecycle.

Payload Subsystem

Supports the integration and operation of mission-specific instruments or technology demonstrations. This subsystem enables the execution of the spacecraft's primary objectives by facilitating payload control, data acquisition, and interface with other system elements.

Propulsion Subsystem

Enables orbital adjustments, maneuvering, and station-keeping as required by the mission plan. This subsystem supports safe navigation throughout all mission phases and allows for responsive trajectory modifications.

Structural Subsystem

Provides the physical framework of the spacecraft, supporting mechanical integration of subsystems and withstanding environmental loads encountered during launch and in orbit. It also facilitates payload and component alignment.

Telemetry, Tracking, and Command Subsystem (TT&C)

Facilitates communication between the spacecraft and mission control. This includes receiving operator command and transmitting spacecraft status, telemetry, and mission data throughout the mission timeline.

Thermal Control Subsystem

Regulates internal and external temperatures of spacecraft components to ensure safe and consistent operation across varying orbital environments. It provides thermal protection during both active and dormant mission states.

These elements are designed to support operators and mission teams by providing command authority, real-time telemetry, health status reporting, and performance feedback. System users may include mission controllers, systems engineers, payload operators, and maintenance analysts who interact with the spacecraft through integrated ground tools and digital platforms. The system also supports increasing levels of onboard autonomy to reduce operator workload and improve mission responsiveness.

This functional overview provides a high-level understanding of the AstraLux Sidera spacecraft's architecture and its key operational responsibilities. Detailed design and implementation specifics are maintained separately in technical documentation and interface control models.

3.3 Interfaces

The AstraLux Sidera spacecraft system is designed to operate through set of coordinated subsystems, each interfacing with both internal elements and external systems to ensure full mission functionality. These interfaces support the transfer of data, power, control, structural loads, thermal regulation, and mission command between the spacecraft and the broader operational environment.

External Interfaces

Ground Segment Interface

The spacecraft communicates with mission control through a ground operations center, using radio frequency (RF) links to support telemetry downlink, command uplink, and tracking. This interface enables human operators to monitor spacecraft status, execute mission plans, and respond to anomalies.

Launch Vehicle Interface

Mechanical and electrical interfaces connect the spacecraft to the launch vehicle, ensuring structural compatibility during integration and proper deployment at orbital insertion. These include separation mechanisms and pre-launch electrical connectivity.

Internal Subsystem Interfaces

Each subsystem functions interdependently, requiring well-defined internal interfaces to enable coordinated behavior. The primary internal interfaces include:

Attitude Determination and Control <-> Payload, TT&C, Propulsion

ADCS provides orientation data and excludes attitude adjustments to support payload pointing, antenna alignment, and maneuver planning.

Command and Data Handing <--> All Subsystems

C&DH distributes command instructions and collects telemetry from each subsystem. It acts as the central data and logic node, coordinating system behavior and providing information to ground operators.

Electrical power <--> All Subsystems

The Electrical Power Subsystem (EPS) supplies conditioned electrical energy to all onboard elements. Interfaces ensure prioritized and stable distribution based on subsystem demand and mission phase.

Payload <--> ADCS, C&DH, TT&C, Thermal

The Payload Subsystem interfaces with control systems for task execution, data handling for downlink, thermal systems for environment regulation, and ADCS for targeting and alignment.

Propulsion <--> ADCS, C&DH, Structural

Propulsion interfaces with control logic for burn execution and navigation coordination, and with the structural subsystem to ensure secure mounting and force distribution.

Structural <--> All Subsystems

The Structural Subsystem houses and supports all other elements, ensuring mechanical integrity under launch and orbital conditions. It interfaces with thermal systems for heat conduction and with payloads for alignment and deployment stability.

Telemetry, Tracking, and Command <-> C&DH, ADCS, Payload

TT&C communicates subsystem status to the ground and receives instructions. Interfaces ensure data is encoded, routed, and prioritized according to mission needs.

Thermal <--> All Subsystems

The Thermal Control Subsystem maintains operating temperatures by interfacing with structural mounts, internal electronics, and exposed surfaces. It passively and actively regulates conditions to ensure subsystem health.

These interface relationships are modeled in system architecture diagrams and interface control documents (ICDs), and are iteratively validated through simulation and digital thread tools as part of the STRIKE environment. Interfaces are defined to support modularity, testability, and maintainability across mission phases.

3.4 Modes of Operations

The AstraLux Sidera spacecraft operates across several defined modes, each supporting a specific phase of the mission life cycle. These modes represent distinct system configuration and behavioral states, ensuring the spacecraft meets its objectives safely and efficiently while remaining responsive to operational needs.

(Mode Transition Diagram)

The major modes of operation include:

1. Development and Testing Mode

Used during the pre-launch phase, this mode enables verification and validation of hardware, software, and system-level integration.

- · Subsystem-level and full-system testing on the ground
- Simulated telemetry and command link verification
- Functional testing of STRIKE interface compatibility
- Environmental qualification (thermal, vibration, EMI/EMC)
- Software-in-the-loop and hardware-in-the-loop simulations

2. Pre-Launch and Integration Mode

Supports activities leading up to and including integration with the launch vehicle.

- Health checks and initialization of subsystems
- · Ground support equipment interfaces for power and telemetry
- Secure data load and mission plan upload
- · Launch-readiness verification
- Ground crew operator interface active; STRIKE connection on standby

3. Launch and Early Orbit Mode (LEOP)

Covers ascent, separation, and initial orbital insertion and checkout.

- Safe mode operations immediately post-deployment
- Basic telemetry beaconing and health assessment
- Deployment of appendages (exempli grata, solar arrays, antennas)
- Establishment of attitude control and stable communications
- Activation of core STRIKE interfaces

4. Nominal Mission Operations Mode

This is the primary operational mode where the spacecraft performs its intended mission tasks.

- Execution of mission planning, sensor operation, and data collection
- Regular interaction with STRIKE for task updates, data uploads, and intelligence integration
- Power management, fault monitoring, and autonomous health checks
- Subsystem coordination via C&DH for payload tasking, orientation control, and propulsion adjustments

5. Contingency or Safe Mode

Activated in response to detected faults, anomalies, or loss of contact with ground operations.

- Suspension of payload operations and non-critical tasks
- Reduced power state; essential systems only
- Automated or manual fault isolation and recovery protocols
- Reacquisition of stable orientation and communications
- Transmission of diagnostic telemetry to ground operators and STRIKE

6. Software Update and Reconfiguration Mode

Used during extended missions or to support evolving objectives

- Secure reception of new software packages or operational scripts
- · Controlled reboot or reinitialization of subsystems
- STRIKE-enabled updates to payload configurations or mission parameters
- Verification before returning to Nominal Operations Mode

7. Decommissioning and Disposal Mode

Initiated at the end of the mission life cycle to ensure responsible and safe end-of-life handling.

- Final data downlink and system state report
- Deactivation of payload and non-essential systems
- Optional orbit lowering, passivation, or handover for controlled disposal
- Preservation of telemetry for historical analysis or modeling

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Each mode includes predefined triggers, exit conditions, and subsystem configuration settings. Transition between modes is governed by command logic (manual or autonomous), health status, and mission phase, with safeguards in place to maintain spacecraft integrity and mission continuity.

3.5 Proposed Capabilities

The AstraLux Sidera spacecraft is envisioned to provide a suite of capabilities that span its full system life cycle—from development and testing through operational deployment and eventual decommissioning. These capabilities are intended to ensure mission success, system reliability, operator confidence, and responsible end-of-life handling.

1. Development and Verification Capabilities

Integrated Test Environment Compatibility

The spacecraft shall support subsystem and full-system testing in simulated mission environments using hardware-in-the-loop and software-in-the-loop capabilities.

Simulated Command and Telemetry Support

The system shall enable simulated command sequences and telemetry outputs to verify responsiveness, logic correctness, and ground system interface compatibility.

Digital Thread and Configuration Tracking

All system configurations and interface states shall be traceable through modeling artifacts for validation, troubleshooting, and audit purposes.

Pre-Launch System Validation

The spacecraft shall support functional validation at the ground station level, including dry run tasking, command sequencing, and fault simulation.

2. Operational Capabilities

Autonomous Health Monitoring and Reporting

The spacecraft shall continuously monitor subsystem status, detect anomalies, and report health status to mission control and STRIKE for operator situational awareness.

Dynamic Task Execution and Mission Replanning

The system shall accept in-mission task updates and adjust planned operations based on task priority, system health, or environmental conditions.

High-Integrity Communications and Data Exchange

The spacecraft shall support reliable, secure bidirectional data transmission with ground control and STRIKE, including command uplinks, telemetry downlinks, and payload data delivery.

Payload Support and Sensor Integration

The platform shall operate with a range of payload types, providing power, data handling, orientation control, and command synchronization for mission tasks.

Orbital Maneuvering and Station-Keeping

The spacecraft shall maintain and adjust its orbit as required by mission objectives or environmental contingencies, supporting orbital stability and avoidance.

• Environment Resilience

The system shall be capable of sustaining operations in variable thermal, radiation, and debris exposure conditions consistent with the selected mission orbit.

3. Contingency and Fault Recovery Capabilities

Safe Mode Entry and Recovery

The system shall detect off-nominal conditions, autonomously enter a safe configuration, and attempt to recover primary functions or await ground commands.

Isolated Subsystem Diagnostics

The spacecraft shall support remote subsystem isolation and diagnostics to enable focused recovery operations and reduce mission interruption.

4. Decommissioning and Disposal Capabilities

End-of-Mission Data Offload

The spacecraft shall provide complete data transfer and mission summary telemetry prior to shutdown or disposal operations.

System Passivation and Deactivation

The platform shall support procedures for battery discharge, propulsion system saving, and payload shutdown to prevent post-mission hazards.

Controlled Orbital Disposal or Handover

Depending on orbital regime, the spacecraft shall either initiate orbital decay maneuvers or enter a long-term safe state for external handoff or archival monitoring.

These proposed capabilities reflect the system's intent to provide persistent functionality, support operator needs, and comply with responsible space operations across the full mission lifecycle. Capability definitions are closely tied to mission requirements and serve as the foundation for design validation, testing protocols, and operational success criteria.

4.0 PHYSICAL ENVIRONMENT

The AstraLux Sidera spacecraft is designed to operate in a range of physical environments associated with ground handling, launch, orbital operations, and decommissioning. These environments influence material selection, structural tolerances, thermal design, and subsystem robustness. The system shall either operate, tolerate with reduced performance, or survive in each phase's conditions as outlined below.

4.1 Ground Integration and Test Environment

During development, integration, and test, the spacecraft will be exposed to controlled terrestrial environments that simulate flight conditions to the extent required for verification.

- Temperature Range: +15 C to +30 C nominal; test tolerance from -20 C to +60 C
- **Atmospheric Pressure:** Sea level; 1 atm (standard)
- Relative Humidity: 5% to 95% non-condensing (must tolerate)
- Cleanroom Requirements: ISO 8 (Class 100,000) or better
- Vibration/Acoustic Testing: Qualification-level random vibration and acoustic load profiles matching the selected launch vehicle
- Shock Loads: Pyrotechnic separation and interface shocks to be simulated during testing
- Electromagnetic Environment: Subject to EMI/EMC testing per launch provider and MIL-STD standards

Capability Requirement: System must operate during final functional testing and survive qualification environmental loads without degradation.

4.2 Transportation Environment

The spacecraft will be transported from integration facilities to the launch site via ground and/or air transport.

- **Temperature Range:** -20 C to +50 C (survivable)
- **Shock and Vibration:** Must tolerate transportation-induced shocks and vibrations using protecting ground support equipment (GSE)
- **Altitude Exposure:** Up to 10,000 feet (air transport equivalent)
- Humidity and Dust: Exposure minimized by packaging; short-term tolerance required
 Capability Requirement: System must survive transportation with no permanent functional degradation.

4.3 Launch and Ascent Environment

During launch and ascent, the spacecraft is exposed to dynamic and extreme environmental conditions

- Acoustic Load Levels: Up to 140 dB (broadband)
- **Vibration:** Random vibration profiles consistent with launch vehicle envelope
- **Shock:** Deployment and separation-induced transient loads
- Atmospheric Pressure: From 1 atm to vacuum (rapid transition)
- Thermal Gradients: Rapid and uneven heating across surfaces

Capability Requirement: System must survive launch and achieve initial operational functionality upon deployment

4.4 On-Orbit Environment

The AstraLux Sidera spacecraft is designed to operate in low Earth orbit (LEO), with the possibility of extension to other orbital regimes in future variants. The operational environment includes the following conditions:

• Temperature Range:

- External Surfaces: -150C (shadow) to +120C (direct sun)
- Internal: regulated via thermal control subsystem

Radiation Environment:

- Total Ionizing Dose (TID): up to 20 krad/year (LEO average)
- Solar Particle Events (SPEs): transient exposure tolerance
- Single Event Effects (SEEs): subsystems must detect and mitigate as needed
- Orbital Debris Impact Risk: Must tolerate minor particulate exposure or include shielding/mitigation strategies
- Vacuum Environment: 10^6 and 10^-9 torn full vacuum survivability required
- Atomic Oxygen: Surface materials must be AO-resistant or coated
- Magnetic Fields: Earth's geomagnetic field influences ADCS performance; systems must compensate accordingly
- Microgravity: Nominal and expected throughout all orbital operations

Capability Requirement: System must operate nominally under these conditions; minor performance degradation is acceptable during high radiation or thermal extremes.

4.5 End-of-Life and Decommissioning Environment

The decommissioning environment depends on the disposal strategy:

Orbital Decay Scenario:

- Must survive aerodynamic heating and atmospheric drag during lower orbits until passive burn-up
- No active operation required after deactivation

Safe-Mode Tumble/Dormancy Scenario:

- Must maintain containment and structural integrity in long-term cold-soak conditions
- Subsystems must remain passivated to prevent energy release or interference with other orbital assets

Capability Requirement: System must safely transition to a non-interfering state and comply with space debris mitigation guidelines.

5.0 SUPPORT ENVIRONMENT

The AstraLux Sidera spacecraft is designed with long-term operational supportability in mind. Once deployed, the system will rely on coordinated planning, ground-based command and control, health monitoring, and modular design to ensure sustained performance throughout its intended mission duration. This section outlines the operational support concepts, maintenance philosophy, and upgrade path envisioned for the system.

5.1 Operational Planning and Commanding

Operations planning for *AstraLux Sidera* will be conducted by mission control personnel using a combination of predefined mission plans and dynamic updates provided through the STRIKE platform.

Mission Planning:

Daily and weekly tasking will be generated based on mission priorities, payload schedules, and spacecraft availability. Plans will include activity windows, orientation requirements, data collection parameters, and communication schedules.

Commanding and Uplink:

Commands will be developed, reviewed, and validated using ground software tools, then uplinked via the TT&C subsystem during designated communication passes. Uplinks may include payload tasking, configuration changes, software patches, or contingency instructions.

Operator Roles:

Roles will include Flight Director, Systems Engineer, Payload Operator, and Mission Analyst. Operators will interface with STRIKE for data visualization, health monitoring, and task deconfliction.

5.2 Monitoring and Diagnostics

Health Monitoring:

Continuous telemetry downlink will provide visibility into subsystem status, performance metrics, and fault indicators. Automated alerts will flag out-of-family behavior, allowing ground teams to respond proactively.

Onboard Fault Detection:

The spacecraft will autonomously monitor key health parameters and initiate transitions to Safe mode when necessary. Ground teams will analyze onboard diagnostic reports for fault isolation and recovery planning.

5.3 Maintenance, Repair, and Replacement Philosophy

As an unscrewed space system, *AstraLux Sidera* is not designed for physical repair or servicing post-deployment. Therefore, its support strategy is based on:

Redundancy:

Critical subsystems will include redundancy (exempli grata, hot/cold spares, cross-strapping) to mitigate single-point failures.

• Fail-Safe Operations:

When faults occur, the system will prioritize health and data preservation by entering predefined safe states until ground intervention is possible.

Virtual Maintenance:

Software diagnostics, resets, and command overrides will serve as primary maintenance tools.

5.4 Sparing and Reuse Philosophy

Spares and Ground Assets:

A limited set of hardware and subsystem-level spares will be maintained on the ground during production and integration phases for risk mitigation and possible reuse on follow-on spacecraft builds.

Reusable Models and Data:

Digital engineering artifacts, including SysML models and test data, will be retained for used in supporting future variants, anomaly resolution, or mission extensions.

5.5 Upgrade and Reconfiguration Capability

Software Upgrades:

The spacecraft will support in-flight software updates via secure command uplinks. This includes upgrades to onboard logic, autonomy scripts, and fault response behavior.

Payload Reconfiguration:

Payload software and tasking schedules can be redefined during operations to support evolving mission goals.

• System Scalability:

The spacecraft's modular architecture supports component substitution and design evolution for future builds using the same system framework.

5.6 Design Team Support Assumptions

• Sustaining Engineering:

A dedicated design team will remain engaged during the mission lifecycle to support anomaly resolution, upgrade development, and mission assurance.

• Configuration Management:

Design teams will maintain the digital twin of AstraLux Sidera throughout operations, ensuring all changes, test results, and updates are traceable and validated.

Data Continuity:

Engineering telemetry and operational feedback will be archived to inform future design decisions and system improvements.

The support environment for *AstraLux Sidera* reflects a commitment to sustainable space operations, system longevity, and mission adaptability. By combining autonomous capabilities with human oversight and digital engineering continuity, the system is positioned for operational resilience and evolution over time.

6.0 OPERATIONAL SCENARIOS, USE CASES, AND/OR DESIGN REFERENCE MISSIONS

6.1 Nominal Conditions

[DRM-0100] Nominal Launch and Early Orbit Operations

Context: The spacecraft is successfully integrated with its launch vehicle and deployed into the designated low Earth orbit.

- The spacecraft autonomously enters initialization mode upon separation.
- Power systems activate and solar arrays deploy to being battery charging.
- Attitude control stabilizes orientation for thermal balance and communication.
- Initial health telemetry is sent to ground via TT&C for verification.
- Operators establish command link and transition system to full mission mode.

Demonstrates: Safe initialization, autonomous deployment behavior, command link establishment, health reporting.

[DRM-0200] Routine Payload Tasking and Data Collection

Context: The spacecraft is performing its primary mission — collecting data with an onboard payload as scheduled.

- STRIKE platform transmits an updated tasking package for payload operation.
- Onboard C&DH schedules and executes the task within the mission window.
- ADCS aligns the spacecraft for optimal payload orientation.
- Data is captured and queued for downlink.
- On next pass, data is transmitted to ground and routed through STRIKE for intelligence production.

Demonstrates: Payload control, coordination between subsystems, task management integration with STRIKE, data delivery cycle.

[DRM-0300] In-Flight Software Update

Context: A software update is scheduled to adjust mission logic and improve autonomy.

- Operators prepare and validate the update package on the ground.
- The update is securely transmitted during a command uplink session.
- The spacecraft stores and verifies the update, then initiates controlled reboot.
- Post-reboot, the updated configuration is confirmed through test commands.

Demonstrates: Secure update support, reconfiguration capability, autonomous software integrity checks.

[DRM-0400] Health Monitoring and Mission Continuity

Context: Daily monitoring and health reporting during long-duration operations.

- System performs regular subsystem checks and generates health reports.
- Operators receive telemetry and review dashboards via STRIKE interface.
- Fault-tree status is confirmed; the spacecraft remains in nominal operations.
- Predictive diagnostics suggest no immediate maintenance required.

Demonstrates: Health monitoring, fault predictions, minimal operator intervention, digital twin support.

6.2 Off-Nominal Conditions

[DRM-0500] Loss of Primary Attitude Control Sensor

Context: The primary star tracker fails during a data collection pass.

- ADCS detects inconsistent orientation readings.
- System switches to secondary sensor suite using gyroscopes and sun sensors.
- A degraded performance notification is sent to mission control.
- Payload task is deferred, but overall mission continues in reduced mode.
- Operators assess fault logs and decide whether to re-enable primary sensor.

Demonstrates: Fault detection, automatic sensor fallback, operator notification, graceful degradation.

[DRM-0600] Unexpected Radiation Event

Context: A solar particle event causes a temporary increase in radiation.

- Radiation monitoring thresholds are exceeded.
- System transitions into a protective safe configuration.
 - Non-essential electronics powered down
 - Payload put into standby
- Spacecraft maintains orientation and critical functions.
- After conditions normalize, operators return the system to nominal operations.

Demonstrates: Environmental resilience, safe mode entry, radiation awareness, operatormanaged recovery.

[DRM-0700] Temporary Loss of Communication with Ground

Context: Ground station is temporarily unavailable due to weather interference.

- Uplink and downlink windows are missed.
- Spacecraft continues executing time-tagged tasks autonomously.
- Health and payload data is stored onboard in protected memory.
- Upon next available pass, queued telemetry and task logs are transmitted.

Demonstrates: Operational autonomy, task queue persistence, fault-tolerant communication behavior.

[DRM-0800] End-of-Mission and Decommissioning

Context: Mission objectives are complete, and spacecraft is scheduled for disposal.

- Operator send decommissioning command set.
- Payload is powered down and final data offload begins.
- Propulsion system initiates orbital decay burn.
- All active subsystems are passivated.
- Spacecraft enters dormant state or prepares for controlled reentry.

Demonstrates: End-of-life handling, safe system shutdown, orbital debris mitigation compliance.

Each scenario supports the validation of system requirements, interfaces, and performance expectations. Nominal scenarios demonstrate the core mission architecture, while off-nominal cases expose needed safeguards, redundancy, and autonomous behavior.

7.0 IMPACT CONSIDERATIONS

The deployment and operation of the *AstraLux Sidera* spacecraft will have implications that extend beyond mission execution. These include impact on the surrounding environment (both terrestrial and orbital), organizational infrastructure, and the broader scientific and technical community. This section addresses those impacts across the system's full life cycle— from development through disposal.

7.1 Environmental Impacts

The AstraLux Sidera system has been designed with environmental responsibility in mind, particularly in its interaction with the space domain. The following environmental impacts are considered:

Orbital Debris Generation

The spacecraft will adhere to current orbital debris mitigation guidelines, including endof-life passivation, planned orbital decay, or transition to a designated disposal orbit. The design avoids components likely to fragment or shed during operations.

Space Environment Interactions

All materials used on the spacecraft will be selected to minimize the risk of material degradation that could result in particle shedding or contamination. No hazardous propulsion byproducts are anticipated to be released into orbit.

Planetary Protection

AstraLux Sidera is no intended for planetary exploration or transfer beyond Earth orbit; therefore, contamination of other celestial bodies is not a mission concern.

Terrestrial Environment Considerations

During manufacturing and testing, all activities will comply with applicable environmental safety and hazardous material handling regulations. Any hazardous materials (exempli grata, batteries, thermal coatings) will be managed through approved disposal protocols.

Launch and Transportation Impact

Environmental impact during launch is governed by the selected launch vehicle provider. The spacecraft itself will not contribute additional environmental risks beyond the scope of standard space payloads.

Impact Summary: Low risk of long-term orbital debris; no planetary contamination; controlled hazardous material handling; environmentally compliant ground operations.

7.2 Organizational Impacts

Deployment of the *AstraLux Sidera* system will necessitate coordination across multiple organizational elements and may require the addition of reallocation of technical and operational personnel.

Workforce and Expertise Needs

The mission will require trained personnel in systems engineering, mission operations, spacecraft command and control, and STRIKE platform integration. This may involve:

- Hiring or contracting subject matter experts
- Cross-training existing aerospace and IT staff
- Establishing on-call support teams for anomaly response

Operational Collaboration

The system may be operated in partnership with defense, civil, or commercial stakeholders, depending on mission context. Clear interface agreements and operational boundaries will be established where multiple agencies or organizations are involved.

Training and Certification

All operators will undergo training specific to *AstraLux Sidera* command tools, fault response protocols, and STRIKE-based tasking workflows. Certification may be required for personnel handling secure data or critical operations.

Mission Support Infrastructure

The system may necessitate enhancements to ground station facilities, secure data handling environment, and digital twin maintenance workflows.

Impact Summary: Requires targeting staffing and training; promotes cross-organizational coordination; enables institutional growth in systems operation and digital integration.

7.3 Scientific/Technical Impacts

The successful deployment of *AstraLux Sidera* will yield both scientific knowledge and operational advancements, depending on the specific payloads and mission configuration.

Mission Utility

The system is primarily intended to enhance operational effectiveness through persistent surveillance, data collection, or reconnaissance in support of national or enterprise objectives.

Technical Advancement

AstraLux Sidera contributes to the evolution of modular spacecraft architecture and digital engineering implementation. It demonstrates:

- Integration of model-based systems engineering (MBSE) with real-time operations
- Secure, multi-domain communications using STRIKE
- In-flight reconfigurability and software-defined control of mission assets

Knowledge and Data Generation

While not a dedicated science platform, the system may provide useful data on:

- Space-based system resilience under variable orbital conditions
- System autonomy in extended-duration missions
- Interoperability between spacecraft and integrated mission planning tools

Innovation Enablement

The mission acts as a reference platform for future digital engineering and intelligence spacecraft initiatives. Lessons learned from *AstraLux Sidera* will inform the development of more agile, interoperable systems.

Impact Summary: Advances digital systems architecture; enhances situational awareness and autonomy; contributes operationally valuable lessons for future space systems.

8.0 RISKS AND POTENTIAL ISSUES

The development, operation, and eventual disposal of the *AstraLux Sidera* spacecraft system present several technical, operational, programmatic, and environmental risks. This section identifies and describes key risk areas and potential issues that could impact mission success. These risks are tracked to inform mitigation strategies, contingency planning, and decision-making throughout the life cycle of the system.

8.1 Technical Risks

Subsystem Integration Complexity

The spacecraft includes multiple interdependent subsystems (ADCS, EPS, C&DH, Payload, et cetera), each requiring precise interface definitions and validation.

Risk: Integration errors could delay system testing or introduce functional conflicts.

Mitigation: Incremental integration testing, interface control documentation (ICD), and system simulation using MBSE models.

Autonomy and Fault Detection Limitations

The system relies on autonomous behavior for fault response and operational continuity.

Risk: Inadequate onboard fault detection or false positives could lead to unnecessary safe-mode transitions or missed data opportunities.

Mitigation: Rigorous validation of autonomy logic, onboard testing of fault trees, and operator override paths.

Software Update Risks

In-flight software updates are critical to mission flexibility but introduce risk of upload failure, corruption, or logic misalignment.

Mitigation: Secure upload protocols, checksum validation, rollback capability, and staging of critical updates in low-risk operational windows.

8.2 Operational Risks

Ground Segment and STRIKE Dependence

The spacecraft's command and control model depends on reliable interaction with the STRIKE platform and associated ground infrastructure.

Risk: Downtime or latency in STRIKE could delay command execution or disrupt situational awareness.

Mitigation: Redundant communication paths, pre-planned autonomy scripts, and periodic offline operation rehearsal.

Communication Blackouts

Unplanned RF interference, poor orbital geometry, or antenna issues may disrupt command or telemetry.

Mitigation: Store-and-forward data buffering, autonomous operation fallback routines, and predictive pass planning.

Contingency Recovery Coordination

In off-nominal scenarios, rapid coordination between mission operators and design engineers may be required.

Risk: Limited staffing or unclear authority roles could delay recovery actions.

Mitigation: Define response protocols, RACI matrices, and maintain design team support through launch +1 year.

8.3 Programmatic and Schedule Risks

Compressed Development Timeline

Accelerated delivery milestones may constrain system testing and validation.

Risk: Early deployment with under-tested configurations may reduce mission robustness.

Mitigation: Prioritize mission-critical capability verification and simulate extended test coverage in digital twin environments.

Staffing Continuity

Sustained mission support will require access to key systems engineers, operators, and STRIKE specialists.

Risk: Turnover or resource shortages could impact operations continuity.

Mitigation: Cross-training, documentation of workflows, and institutional knowledge capture early in the program.

8.4 Disposal and Closeout Risks

End-of-Life Execution Failure

Planned orbital decay or deactivation may be impacted by propulsion limitations, command link loss, or system degradation.

Risk: Spacecraft may remain uncontrolled in orbit beyond expected duration, increasing orbital debris risk.

Mitigation: Reserve deorbit delta-V, include autonomous passivation logic, and conduct end-of-mission rehearsals.

Data and Knowledge Loss

Final telemetry, lessons learned, or mission data may be lost if closeout is rushed or improperly archived.

Mitigation: Plan structured closeout phase with formal data capture, report generation, and system configuration archiving.

8.5 Risk Management Approach

All risks will be tracked in a formal Risk Register, assessed using likelihood/severity scoring, and mitigated through system design and program management processes. Unacceptable risks will be escalated during formal technical reviews, and contingency plans will be established for mission-critical scenarios.

APPENDIX A: ACRONYMS

Abbreviation	Definition
ADCS	Attitude Determination and Control Subsystem
C&DH	Command and Data Handling Subsystem
DRM	Design Reference Mission
EPS	Electrical Power Subsystem
ICD	Interface Control Document
SEE	Single Event Effects
SPE	Solar Particle Events
TID	Total Ionizing Dose